

# Absolute encoders - parallel

Solid shaft with clamping flange

Optical singleturn encoders 13 bit

## GA240 - parallel



GA240 with clamping flange

### Features

- Encoder singleturn / parallel
- Optical sensing method
- Resolution: 13 bit
- Clamping flange
- Short-circuit proof push-pull outputs
- Output release by enable signal
- Permanent check of code continuity

### Technical data - electrical ratings

Voltage supply	10...30 VDC
Reverse polarity protection	Yes
Consumption w/o load	≤60 mA (24 VDC)
Initializing time typ.	20 ms after power on
Interface	13 parallel outputs
Function	Singleturn
Steps per turn	8192 / 13 bit
Absolute accuracy	±0.025 °
Sensing method	Optical
Code	Gray or binary
Code sequence	CW/CCW coded by connection
Inputs	Control signals UP/DOWN inv. and zero STORE inv. ENABLE inv.
Output stages	Push-pull short-circuit proof
Interference immunity	DIN EN 61000-6-2
Emitted interference	DIN EN 61000-6-4
Diagnostic functions	Self-diagnosis Code continuity check
Approval	UL approval / E63076

### Technical data - mechanical design

Size (flange)	ø58 mm
Shaft type	ø10 mm solid shaft
Flange	Clamping flange
Protection DIN EN 60529	IP 54 (without shaft seal), IP 65 (with shaft seal)
Operating speed	≤10000 rpm (mechanical) ≤6000 rpm (electric)
Starting torque	≤0.015 Nm (+25 °C, IP 54) ≤0.03 Nm (+25 °C, IP 65)
Rotor moment of inertia	14.5 gcm <sup>2</sup>
Admitted shaft load	≤20 N axial ≤40 N radial
Materials	Housing: aluminium Flange: aluminium
Operating temperature	-25...+85 °C -40...+85 °C (optional)
Relative humidity	95 % non-condensing
Resistance	DIN EN 60068-2-6 Vibration 10 g, 16-2000 Hz DIN EN 60068-2-27 Shock 200 g, 6 ms
Weight approx.	250 g
Connection	Connector M27, 21-pin Cable 1 m

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## Part number

GA240.       02

### Connection

- C0 Connector M27, 21-pin, axial
- C1 Connector M27, 21-pin, radial
- 51 Cable 21-core, 1 m, axial
- 61 Cable 21-core, 1 m, radial

### Voltage supply / signals

- 10 10...30 VDC / gray code push-pull
- 12 10...30 VDC / binary code push-pull

### Flange / Solid shaft

- 0 Clamping flange / ø10 mm, IP 54
- A Clamping flange / ø10 mm, IP 65

## Accessories

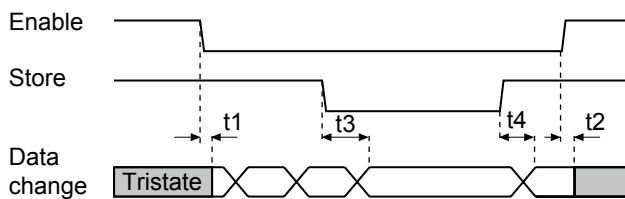
### Connectors and cables

11034174	Female connector M27, 21-pin, without cable (Z 132.001)
11034175	Female connector M27, 21-pin, 2 m cable (Z 132.003)
11034176	Female connector M27, 21-pin, 5 m cable (Z 132.005)
11034177	Female connector M27, 21-pin, 10 m cable (Z 132.007)

### Mounting accessories

10117669	Eccentric fixing, single (Z 119.006)
10141255	Adaptor plate for clamping flange for modification into synchro flange (Z 119.013)
10125051	Mounting adaptor for encoders with clamping flange (M3) (Z 119.017)
11034088	Adaptor plate for clamping flange, mounting by eccentric fixings (order separately) (Z 119.025)
10141132	Spring washer coupling D1=6 / D2=10 (Z 121.001)

## Data transfer



Signal form	Typ. pul time	Time
Enable	t1/t2	60 µs
Store	t3/t4	60 µs

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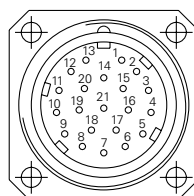
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Terminal significance	
UB	Encoder voltage supply.
GND	Encoder ground connection relating to UB.
Outputs D0-D12	13 parallel output signals.
DATAVALID inv.	Diagnostic output. An error warning is given at level Low. Important: Interferences must be filtered by the downstream electronics.
Zero setting	Input for setting a zero point anywhere within the programmed encoder resolution. The zero setting operation is triggered by a High impulse and has to be in line with the selected direction of rotation (UP/DOWN). Connect to GND after setting operation for maximum interference immunity. Impulse duration $\geq 100$ ms.
UP/DOWN inv.	UP/DOWN inv. counting direction input. This input is standard on High. UP/DOWN inv. means ascending output data with clockwise shaft rotation when looking at flange. UP/DOWN inv.-Low means ascending values with counterclockwise shaft rotation when looking at flange.
ENABLE inv.	Input for activating the output drivers that are triggered by input level Low. Upon being on High (or less potential) the output drivers switch to high-impedance (Tristate).
STORE inv.	Input for output data storage. Upon a Low input level the encoder data are stored in the intermediate memory. Upon being on High (or less potential) the current encoder position data are switched to the output drivers. This line must be applied for reliable data readout in binary code.

Terminal assignment		
Connector	Core colour	Assignment
Pin 1	violet	Output D0
Pin 2	white/brown	Output D1
Pin 3	white/green	Output D2
Pin 4	white/yellow	Output D3
Pin 5	white/grey	Output D4
Pin 6	white/pink	Output D5
Pin 7	white/blue	Output D6
Pin 8	white/red	Output D7
Pin 9	white/black	Output D8
Pin 10	brown/green	Output D9
Pin 11	brown/yellow	Output D10
Pin 12	brown/grey	Output D11
Pin 13	brown/pink	Output D12
Pin 14	green/grey	-
Pin 15	blue	GND
Pin 16	blue/yellow	DATAVALID inv.
Pin 17	brown	UP/DOWN inv.
Pin 18	pink	STORE inv.
Pin 19	red	UB
Pin 20	red/yellow	Zero setting
Pin 21	yellow	ENABLE inv.



Trigger level	
Control inputs	Input circuit
Input level High	>0.7 UB
Input level Low	<0.3 UB
Input resistance	10 k $\Omega$
Parallel outputs	Output circuit
	Push-pull circuit-proof
Output level High	>UB -3.5 V (I = -20 mA)
Output level Low	<0.5 V (I = 20 mA)
Load High	<-30 mA
Load Low	<30 mA
Tristate	<10 $\mu$ A

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### Dimensions

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