

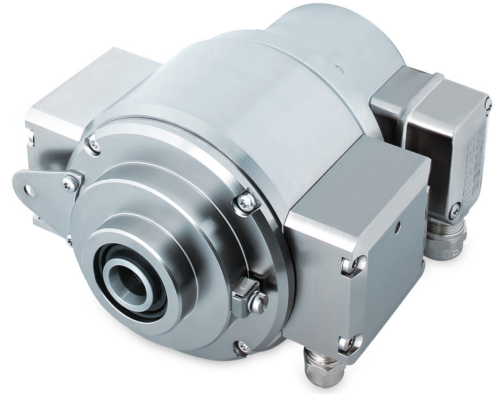
HMG 11 + FSL

Encoder with integrated centrifugal switch

Single and multiturn 13 bit ST / 12 or 16 bit MT / SSI / Profibus / CANopen® / DeviceNet

Overview

- Multiturn / SSI / Profibus / CANopen® / DeviceNet
- Singleturn 13 bit, multiturn 12 bit / 16 bit
- Mechanical speed monitoring based on centrifugal force
- Blind hollow shaft up to $\varnothing 20$ mm or cone shaft $\varnothing 17$ mm (1:10)
- Multiturn sensing with microGen technologie, without gear or battery
- Available with redundant absolute signals
- Special protection against corrosion



Technical data

Technical data - electrical ratings

| | |
|-----------------------|--------------|
| Interference immunity | EN 61000-6-2 |
| Emitted interference | EN 61000-6-3 |
| Approval | CE |

Technical data - electrical ratings (encoder)

| | |
|-------------------------|---|
| Voltage supply | 9...30 VDC |
| Consumption w/o load | ≤100 mA (per interface SSI) ≤250 mA (per interface bus) |
| Sensing method | Optical |
| Initializing time | ≤200 ms after power on |
| Interface | SSI Profibus-DPV0 CANopen® DeviceNet |
| Function | Multiturn |
| Transmission rate | 9.6 ... 12000 kBaud (Profibus) 10 ... 1000 kBaud (CANopen®) 125 ... 500 kBaud (DeviceNet) |
| Profile conformity | Profibus-DPV0 CANopen® CiA DSP 406 V 3.0 Device Profile Encoder V 1.0 |
| Device address | Rotary switches in bus cover |
| Steps per revolution | 8192 / 13 bit |
| Number of revolutions | ≤65536 / 16 bit |
| Additional outputs | Square-wave TTL (RS422) Square-wave HTL |
| Code | Gray (version SSI) |
| Code sequence | CW default |
| Inputs | SSI clock (version SSI) |
| Programmable parameters | Depending on the selected absolute interface |
| Diagnostic function | Position or parameter error |
| Status indicator | DUO-LED integrated in bus cover |

Technical data - electrical ratings (centrifugal switch)

| | |
|---------------------------|---|
| Switching accuracy | ± 4 % ($\Delta n = 2$ rpm/s); 20 % ($\Delta n = 1500$ rpm/s) |
| Switching deviation | ≤3 % (cw-ccw rotation) |
| Switching hysteresis | 40 % of switching speed |
| Switching outputs | 1 output, speed control |
| Output switching capacity | ≤6 A / 230 VAC; ≤1 A / 125 VDC (EAC: <50 VAC / 75 VDC) |
| Minimum switching current | 50 mA |

Technical data - mechanical design

| | |
|-------------------------------|--|
| Size (flange) | $\varnothing 122$ mm |
| Shaft type | $\varnothing 16...20$ mm (blind hollow shaft) $\varnothing 17$ mm (cone shaft 1:10) |
| Admitted shaft load | ≤250 N axial, ≤400 N radial |
| Protection EN 60529 | IP 67 |
| Speed (n) | ≤1.25 · ns |
| Range of switching speed (ns) | 850...2800 rpm ($\Delta n = 2$ rpm/s) |
| Operating torque typ. | 15 Ncm |
| Rotor moment of inertia | 790 gcm ² |
| Material | Housing: aluminium alloy Shaft: stainless steel |
| Operating temperature | -20...+85 °C |
| Resistance | IEC 60068-2-6 Vibration 5 g, 10-2000 Hz IEC 60068-2-27 Shock 50 g, 11 ms |
| Corrosion protection | IEC 60068-2-52 Salt mist for ambient conditions CX (C5-M) according to ISO 12944-2 |
| Connection | Bus cover; Terminal box; Flange connector M23, 12-pin |
| Weight approx. | 3.5 kg (depending on version) |

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Optional

- Additional incremental output (TTL / HTL)

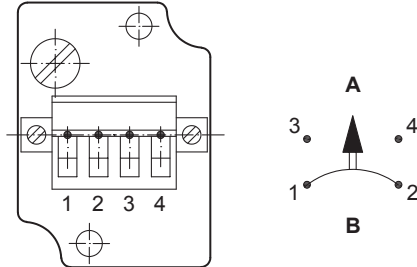
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Terminal assignment

View D (see dimension)
Connecting terminal

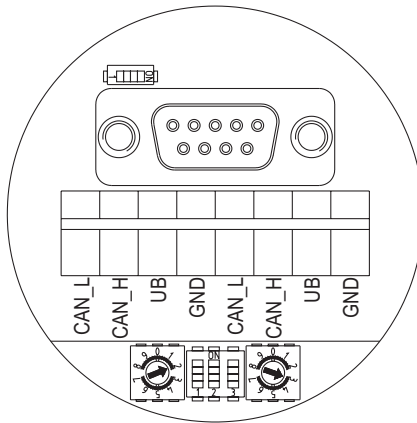


A = make contact, **B** = break contact

CANopen® features

Terminal assignment

View A - Connecting terminal in bus cover



Terminal significance

| | |
|-------|--------------------------------|
| CAN_L | CAN Bus signal (dominant Low) |
| CAN_H | CAN Bus signal (dominant High) |
| UB | Voltage supply 9...30 VDC |
| GND | Ground connection for UB |

Terminals of the same significance are internally connected and identical in their functions. Max. load on the internal terminal connections UB-UB and GND-GND is 1 A each.

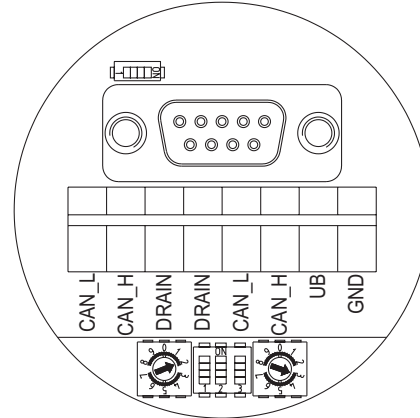
Features

| | |
|-----------------|--|
| Bus protocol | CANopen® |
| Features | Device Class 2 CAN 2.0B |
| Device profile | CANopen® CiA DSP 406, V 3.0 |
| Operating modes | <ul style="list-style-type: none"> ■ Polling mode (asynch, via SDO) ■ Cyclic mode (asynch-cyclic) ■ Synch mode (synch-cyclic) ■ Acyclic mode (synch-acyclic) |
| Diagnosis | The encoder supports the following error warnings: <ul style="list-style-type: none"> ■ Position error |
| Factory setting | User address 00 |

DeviceNet features

Terminal assignment

View A - Connecting terminal in bus cover



Terminal significance

| | |
|-------|--------------------------------|
| CAN_L | CAN Bus Signal (dominant Low) |
| CAN_H | CAN Bus Signal (dominant High) |
| DRAIN | Shield |
| UB | Voltage supply 9...30 VDC |
| GND | Ground for UB |

Terminals of the same significance are internally connected and identical in their functions. Max. load on the internal terminal connections UB-UB and GND-GND is 1 A each.

Features

| | |
|---------------------|--|
| Bus protocol | DeviceNet |
| Device profile | Device Profil for Encoders V 1.0 |
| Operating modes | <ul style="list-style-type: none"> ■ I/O-Polling ■ Cyclic ■ Change of State |
| Preset value | The „Preset“ parameter can be used to set the encoder to a predefined value that corresponds to a specific axis position of the system. The offset of encoder zero point and mechanical zero point is stored in the encoder. |
| Parameter functions | <p>Rotating direction:</p> <p>The relationship between the rotating direction and rising or falling output code values can be set in the operating parameter.</p> <p>Scaling:</p> <p>The parameter values set the number of steps per turn and the overall resolution.</p> |
| Diagnostic | The encoder supports the following error warnings: <ul style="list-style-type: none"> ■ Position and parameter error |
| Factory setting | User address 00 |

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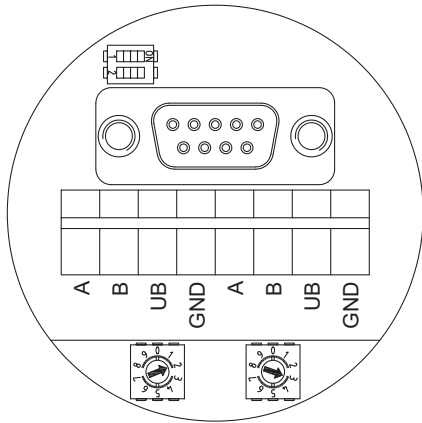
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Profibus-DP features

Terminal assignment

View A - Connecting terminal in bus cover



Terminal significance

| | |
|-----|--|
| A | Negative serial data transmission, pair 1 and pair 2 |
| B | Positive serial data transmission, pair 1 and pair 2 |
| UB | Voltage supply 9...30 VDC |
| GND | Ground connection for UB |

Terminals of the same significance are internally connected and identical in their functions. Max. load on the internal terminal connections UB-UB and GND-GND is 1 A each.

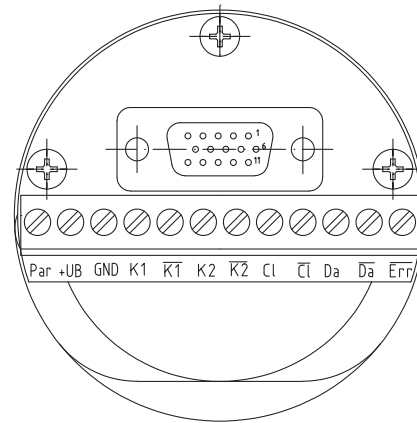
Features

| | |
|-------------------------|---|
| Bus protocol | Profibus-DP V0 |
| Features | Device Class 1 and 2 |
| Data exchange functions | Input: Position value Output: Preset value |
| Preset value | The „Preset“ parameter can be used to set the encoder to a predefined value that corresponds to a specific axis position of the system. |
| Parameter functions | Rotating direction: The relationship between the rotating direction and rising or falling output code values can be set in the operating parameter. Scaling: The parameter values set the number of steps per turn and the overall resolution. |
| Diagnostic | The encoder supports the following error messages: <ul style="list-style-type: none"> Position error |
| Factory setting | User address 00 |

SSI/Incremental features

Terminal assignment

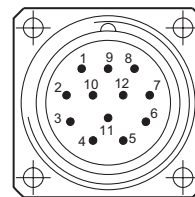
View B - Connecting terminal in cover



View C - Option

Flange connector M23, 12-pin, male contacts, counter-clockwise

| Male | Assignment |
|------|------------|
| 1 | K2 |
| 2 | Clock * |
| 3 | Data * |
| 4 | Data * |
| 5 | K1 |
| 6 | K1 |
| 7 | Param * |
| 8 | K2 |
| 9 | Error * |
| 10 | GND |
| 11 | Clock * |
| 12 | +UB * |



* only for SSI

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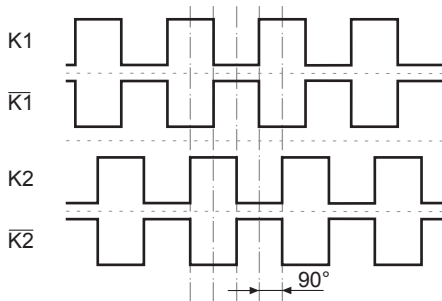
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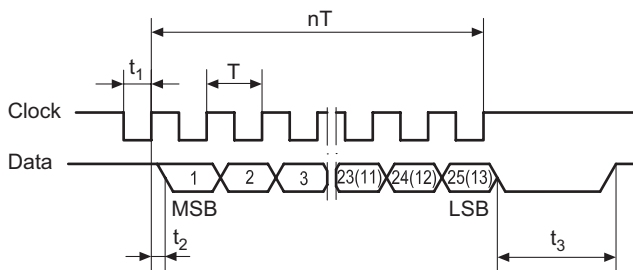
Output signals

HTL/TTL

At positive rotating direction (see dimension)



Data transfer



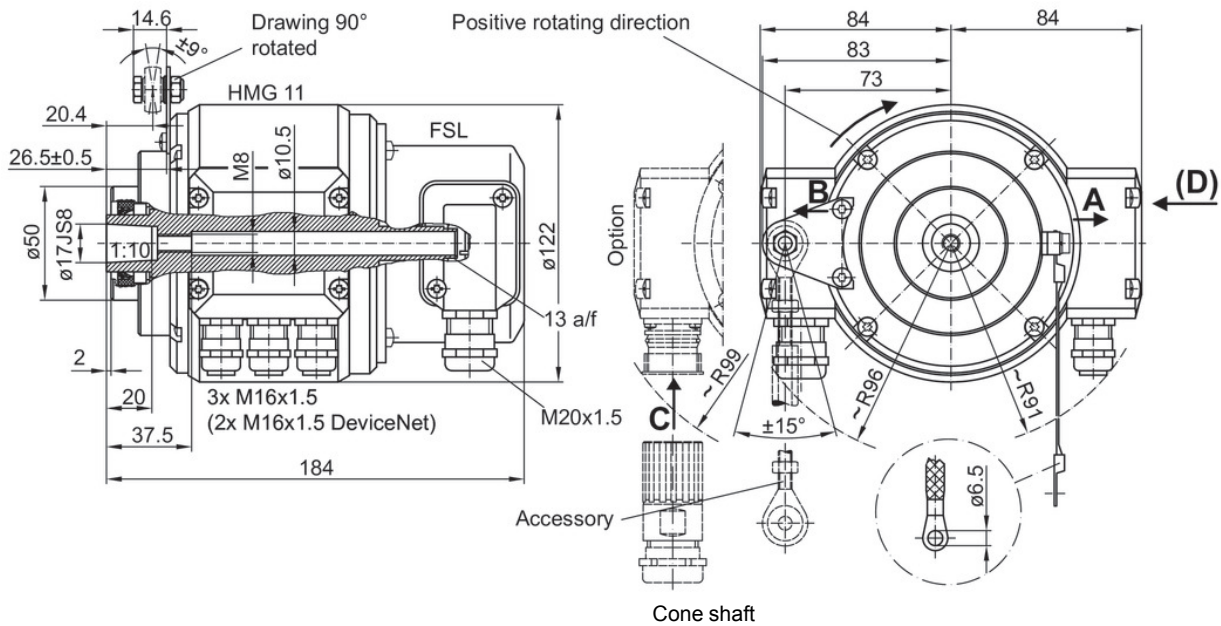
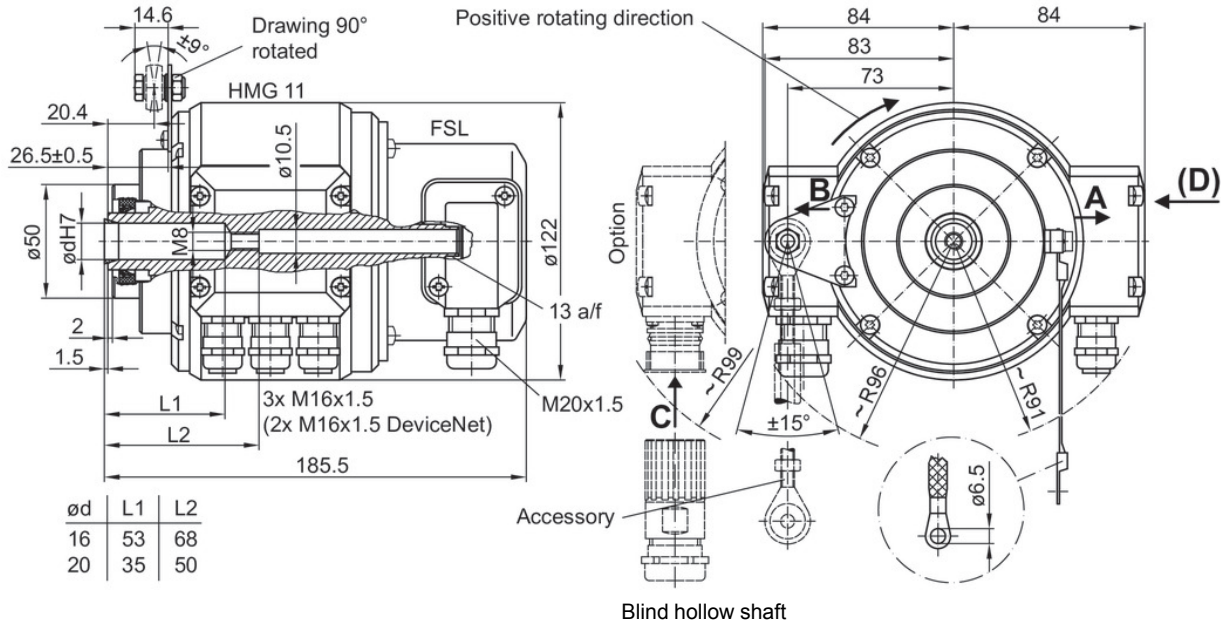
| | |
|------------------|-------------------|
| T = | 1.25...10 μ s |
| t ₁ = | 0.63...5 μ s |
| t ₂ = | 0.4 μ s |
| t ₃ = | 12...30 μ s |
| n = | Number of bits |
| Clock frequency | 100...800 kHz |

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Dimensions



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Ordering reference

| | HMG11 | # | ## | ##### | ##### | ##### | + FSL | ##### |
|--|-------|----|----|-------|-------|--------|-------|-------|
| Product | HMG11 | | | | | | | |
| Interface/interfaces | | | | | | | | |
| SSI | | S | | | | | | |
| Profibus | | P | | | | | | |
| CANopen® | | C | | | | | | |
| DeviceNet | | D | | | | | | |
| 2 x SSI | | SS | | | | | | |
| Profibus and SSI | | PS | | | | | | |
| CANopen® and SSI | | CS | | | | | | |
| DeviceNet and SSI | | DS | | | | | | |
| 2 x Profibus | | PP | | | | | | |
| CANopen® and Profibus | | CP | | | | | | |
| DeviceNet and Profibus | | DP | | | | | | |
| 2 x CANopen® | | CC | | | | | | |
| DeviceNet and CANopen® | | DC | | | | | | |
| 2 x DeviceNet | | DD | | | | | | |
| Absolute share | | | | | | | | |
| 13 bit singleturn | | | 13 | | | | | |
| 13 bit singleturn + 12 bit multitem | | | 25 | | | | | |
| 13 bit singleturn + 16 bit multitem | | | 29 | | | | | |
| Additional output | | | | | | | | |
| Without | | | | Z0 | | | | |
| TTL level, 1024 pulses ⁽¹⁾ | | | | T1024 | | | | |
| TTL level, 2048 pulses ⁽¹⁾ | | | | T2048 | | | | |
| HTL level, 1024 pulses ⁽¹⁾ | | | | H1024 | | | | |
| HTL level, 2048 pulses ⁽¹⁾ | | | | H2048 | | | | |
| Shaft diameter | | | | | | | | |
| Blind hollow shaft ø16 mm | | | | 16H7 | | | | |
| Blind hollow shaft ø20 mm | | | | 20H7 | | | | |
| Cone shaft ø17 mm (1:10) | | | | 17K | | | | |
| Connection | | | | | | | | |
| Without SSI/incremental | | | | | | | | |
| Terminal box, radial | | | | | | KLK | | |
| Flange connector M23, radial (only SSI/incremental) | | | | | | ST-M23 | | |
| Version speed switch | | | | | | | + FSL | |
| Mechanical centrifugal switch | | | | | | | | |
| Switching speed (ns) | | | | | | | | |
| 850...949 rpm ($\Delta n = 2$ rpm/s) ⁽²⁾ | | | | | | | | 6 |
| 950...1099 rpm ($\Delta n = 2$ rpm/s) ⁽²⁾ | | | | | | | | 5 |
| 1100...1299 rpm ($\Delta n = 2$ rpm/s) ⁽²⁾ | | | | | | | | 4 |
| 1300...1799 rpm ($\Delta n = 2$ rpm/s) ⁽²⁾ | | | | | | | | 3 |
| 1800...2499 rpm ($\Delta n = 2$ rpm/s) ⁽²⁾ | | | | | | | | 2 |
| 2500...4500 rpm ($\Delta n = 2$ rpm/s) ⁽²⁾ | | | | | | | | 1 |

(1) The incremental signals are duplicated with configuration SS. Please note: additional incremental output signals are not feasible with PP, CP, DP, CC, DC and DD interface.

(2) Please specify the exact switching speed in addition to the part number (factory setting).

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Accessories

Mounting accessories

| | |
|----------|---|
| 11077197 | Mounting kit for torque arm size M6 and earthing strap |
| 11077087 | Mounting and dismantling set |
| 11043628 | Torque arm M6, length 67...70 mm |
| 11004078 | Torque arm M6, length 120...130 mm (≥ 71 mm) |
| 11002915 | Torque arm M6, length 425...460 mm (≥ 131 mm) |
| 11054917 | Torque arm M6 insulated, length 67...70 mm |
| 11072795 | Torque arm M6 insulated, length 120...130 mm (≥ 71 mm) |
| 11082677 | Torque arm M6 insulated, length 425...460 mm (≥ 131 mm) |