

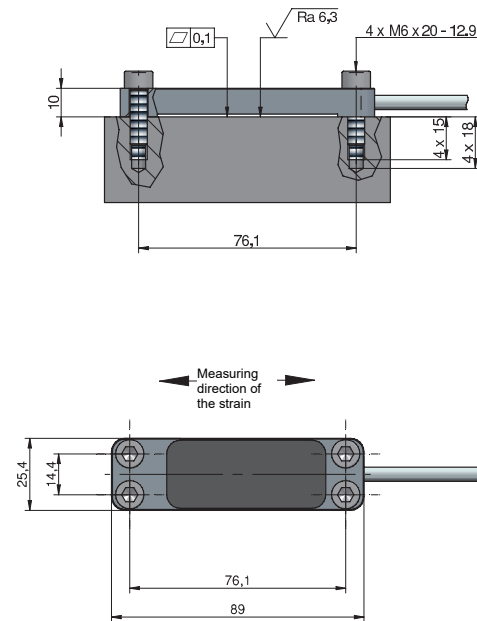
Quickstart



DST76-B500U

Strain sensor with voltage output and IO-Link

Dimensional drawing



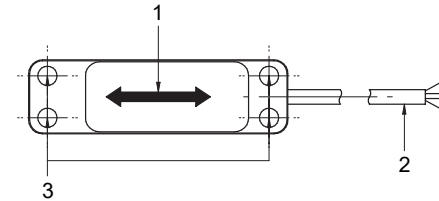
Applicable documents

- Download from www.baumer.com:
 - Operating manual
 - Data sheet
 - EU Declaration of Conformity
- Attached to product:
 - General information sheet (11042373)

Scope of delivery

- 1 x sensor
- 4 x screws M6x20, quality 12.9

Structure



- | | |
|------------------------|---|
| 1 Strain direction | 2 Connection cable
(PUR, 5 conductors) |
| 3 Attachment drillings | |

Functionality

The sensor is screwed to a machine element and measures its strain. Changes in the strain are measured with strain gauges and converted into an electrical signal. If the sensor experiences a tensile force, the signal is positive; if it experiences a compression, the signal is negative.

The signal output is either an analog or digital (IO-Link) signal. The sensor is parameterized via the integrated IO-Link interface.

FAQ

The sensor does not output a stable signal. What is the reason for this?

The sensor is not screwed on tightly. To obtain stable measurement results, the sensor must be firmly screwed onto a machine element.

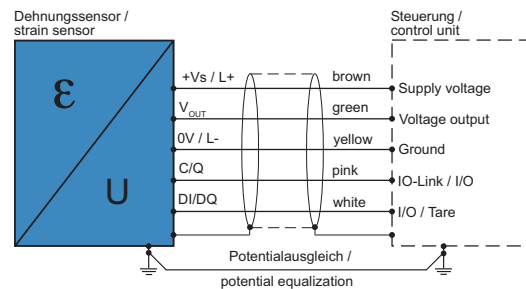
EN

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Output signal: $V_{OUT} = \pm 10$ V, parameterizable
Operating voltage range: $+Vs = 18$ to 30 VDC

Disconnect the system from power before connecting the device. Power supply according to UL 1310, Class 2 or external protection via a UL-approved or listed fuse with max. 100 W/Vp or max. 5 A below 20 V.
Note on electromagnetic compatibility: Shielded connection cable is recommended. Ground the cable shield on both sides over a large surface and ensure potential equalization.
Connection cable length max. 20 m.

Wire assignment

brown	+Vs / L+
green	V_{OUT}
yellow	0V / L-
pink	C/Q (IO-Link / SIO1)
white	DI/DQ (SIO2)
Housing	Shield

Factory settings (for standard type)

Output signal (at V_{OUT}):	± 10 VDC
SIO1:	Inactive
SIO2:	Teach-in offset, tare

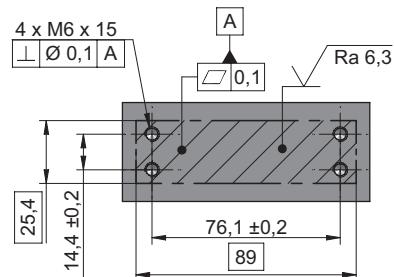
Preparing the mounting

NOTICE

The sensor supplies imprecise measurement results if the measuring surface is soiled or if the sensor is installed incorrectly.

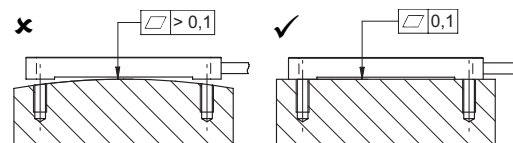
- Prevent soiling from grease and oil.
- Mount the sensor on a machined, flat surface.
- Observe the surface roughness.

Mounting surface to be machined:

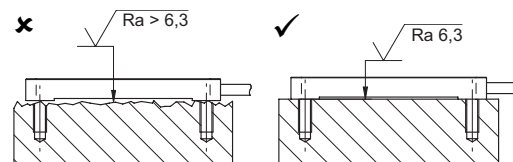


Instruction:

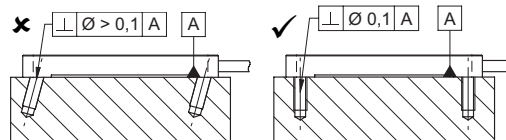
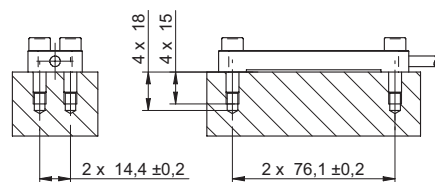
- Check the flatness tolerance.
Flatness tolerance ≤ 0.1 mm



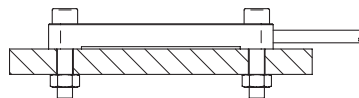
- Check the surface roughness.
Surface roughness ≤ 6.3 μm



- Drill 4 threads into the machine element. Make sure to drill the holes perpendicular to the contact surface of the sensor.
 - Drill hole spacing: 76.1 ± 0.2 mm; 14.4 ± 0.2 mm
 - Depth of drill holes: ≥ 18 mm
 - Depth of thread: ≥ 15 mm



Mounting option with through holes:



Mounting the sensor

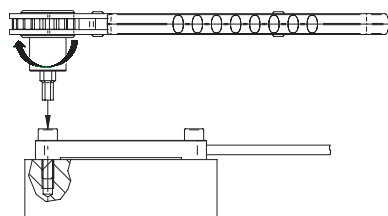
INFO

The included screws (M6×20) are designed for mounting on steel. Use longer screws (M6×25) for mounting on light or non-ferrous metals.

The following describes mounting on steel:

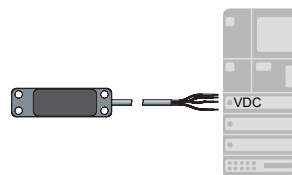
Instruction:

- Make sure that the machine element is not loaded.
- Screw in the screws hand-tight.
- Tighten the screws (hexagon socket SW5) cross-wise in 2 stages with a torque wrench to a tightening torque of 20 Nm.



Putting the sensor into operation for the first time

For commissioning, the sensor is connected directly to the controller. The output signal is an analog signal and is proportional to the strain.



Instruction:

- To minimize the effect of settlement, fully load the sensor 10 times, if possible.
- With the power on, allow the sensor to warm up for 5 minutes to stabilize the zero point.

- Tare the sensor at zero load to compensate for signal changes due to mounting.

Result:

- ✓ The sensor is ready for operation.

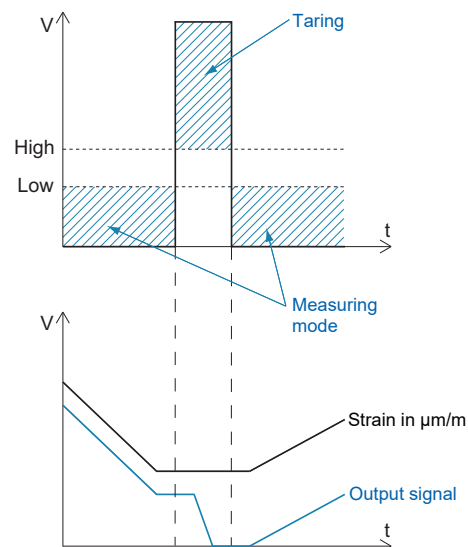
Operation

Taring the sensor

Tare the sensor cyclically in the unloaded state to compensate for zero drift or temperature influences.

Instruction:

- Make sure that the sensor does not experience any change in strain.
- Make sure that the machine element is at the correct zero position.
- Tare the sensor at zero load (voltage signal *High* or via IO-Link).



NOTICE

SIO1 and SIO2 with input function

SIOs operated as input must not be floating but always be assigned to a defined level *High* or *Low*. Default SIO2 parameterization is as input *Teach-In Offset/Tare* function. If this functionality is not required, assign the input permanently to GND to prevent unintended taring.

Parameterization (optional)

To achieve even better measurement results, you have the option of parameterizing the sensor through the integrated amplifier electronics via the IO-Link interface to suit the application. For this purpose, the sensor is connected to an IO-Link master.



The operating manual, the IODD file for parameterizing the sensor, and information on accessories can be found at:

- www.baumer.com (-> product detail page) and
- ioddfinder.io-link.com

In the following, you will find a selection of the parameterizable functions of the sensor:

- Define the unit of the output process value (N, kN, $\mu\text{m/m}$, ...)
- Tare the sensor, e.g. after it has been mounted (distortion, *Teach-in offset*)
- Calibrate the sensor to a known force on the machine (*Teach-in by Reference*)
- Adapt the analog output signal to the actual strain present (e.g. max. output signal at $350 \mu\text{m/m}$)
- Peak value memory for reliable maximum value recognition in real time
- Low-pass filter for optimized signal-to-noise ratio and smoothing in case of signal fluctuations
- Sample & hold for precise measured values at defined times for precise settings
- Configurable switching outputs
- Diagnostic data (detailed device status, operating hours counter, quality bit)
- Error detection (alarm bit for display of invalid measuring signals, freely configurable signal value at analog output for error detection)

Maintenance

The sensor is maintenance-free. No special preventive maintenance is required.