Operating instructions. ScaDiag Application software for the Scatec Laser Copy Counter



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1 Introduction

1.1 What is the ScaDiag Software used for ?

Every *Scatec* can be operated as a stand-alone sensor. However, it can also be interfaced to a PC. *ScaDiag*, the software used for remote controlling a *Scatec*, is a powerful tool with very helpful features especially in the following two areas:

- parameterization: With a few key strokes, all of the *Scatec* parameters (within the bounds given by the connected *Scatec* model) can be retrieved and manipulated. Additionally, a file documenting the complete sensor status can be created very easily. This file can be e-mailed to an applications engineer at Baumer Electric making numerous queries on the *Scatec* parameter setting details unnecessary.
- recording data: Data logging is a core application of *ScaDiag*. The possibility of reading out, saving, and graphically displaying data even while the *Scatec* is running, is a tremendous help if there comes a need to take a closer look at certain aspects of a production run. The collected data can be analyzed by the customer himself or they can be forwarded to Baumer electric for that purpose.

1.2 What resources are needed ?

In order to interface a *Scatec* to a PC, the following items are needed:

Hardware:	Any Scatec (second generation)		
	PC with a USB port		
	Y-cable	(*)	
	Serial-to-USB- converter	(*)	
Software:	ScaDiag	(*)	
	Driver for Serial-to-USB converter	(*)	

(*) included in the corresponding ScaDiag kit.



2 Setting up ScaDiag

2.1 System requirements

ScaDiag, as well as the driver software for the Serial-to-USB- converter, run under the following operating systems:

- Windows 2000
- Windows XP

The Serial-to-USB converter connects to the USB port of the PC.

2.2 Installation of the Serial-to-USB Converter

2.2.1 Installation

- 1. Close the ScaDiag application if running
- 2. Insert the CD containing the ScaDiag- Software package into the PC
- 3. Connect the Ser./USB-Converter/S14 to the USB-port on your PC
- 4. Your PC should find a new USB device.
- 5. Follow the instructions given by Windows.

Found New Hardware Wizard	
	Welcome to the Found New Hardware Wizard
	This wizard helps you install software for:
	Baumer Electric - ScaDiag Serial-USB
	If your hardware came with an installation CD or floppy disk, insert it now.
	What do you want the wizard to do?
	 _ Install the software automatically (Recommended) ● [Install from a list or specific location (Advanced)]
	Click Next to continue.
	< <u>Back</u> <u>Next</u> > Cancel

Choose Install from a list or specific location





Choose Search for the best driver in these locations

and check Search removable media(floppy, CD-ROM...)

After clicking *Next*, the driver for the *Ser./USB-Converter/S14* will be installed



6. Now the *Scatec* can be connected to the Serial-to-USB converter.



2.2.2 Checking for correct driver installation

If the driver has been correctly installed, FTDI FT8U2XX Device should be in the list of USB-controllers.

(on the Windows 2000 taskbar, click **Start > Settings > System** or on the Windows XP taskbar, click **Start > Control Panel > System**. Double-click the **System** icon. On the hardware tab, click **device manger**. Double-click the **USB-Controller** icon and look for the *FTDI FT8U2XX Device*.)



2.2.3 Uninstalling

In case the FTDI FTD2XX USB Drivers need to be uninstalled, proceed as follows:

1. On the Windows 2000 taskbar, click *Start* > *Settings* > *Control Panel*. Double-click the *Software* icon. The following window should be displayed:

On the Windows XP taskbar, click *Start* > *Control Panel* > *Add or Remove Programs* >. Double-click the *Software* icon. The following window should be displayed:



Click FTDI FTD2XX USB Drivers. Click Change / Remove.



2. Unplug the Ser./USB-Converter/S14



3. The FDTI driver has been uninstalled:

Uninstalli	ng VID_0403&PID	_6001	
Deleting	egistry entries		
Deleting	nes		
Uninstan	complete, press r	inish to exit.	

2.3 Installation of ScaDiag

1. Copy both files

2.

ScaDiag_E_xxxxxy.exe and ScaDiagTyp.txt

from the CD to the **same** directory on your PC (for example: to C:\Program files\Scatec) Now you are ready to run *ScaDiag_E_xxxxxy.exe* or *ScaDiag_D_xxxxxy.exe*

(The letter *E* stands for English and *D* for German)

Note: communication with a *Scatec* is not possible if the driver for the Serial-to-USB converter has not been previously installed.



2.4 How to connect a Scatec to a PC

ScaDiag allows to read out and to log data without interfering with the running production. How the Scatec is hooked up to the PC is shown subsequently for each Scatec model. All accessories needed are included in the corresponding ScaDiag-kit.

Scatec-2:

required accessories:

Y-Cable: article 155670 article 156256) USB-to-Serial Converter: for *Scatec-2* /S14 for *Scatec-2* /S42 article 155304

After inserting the Y-cable the *Scatec-2* is reconnected fully to the customer's control system.





Passion for Sensors

Scatec-10:

required accessories:

Adapter cable:	
USB-to-Serial Converter:	

article 156261 article 155304



Scatec-15:

required accessories:

Y-Cable:article	article 156257
USB-to-Serial-Converter:	article 155304

Without interrupting the connection to the customer's control

system, the adapter cable 156261 is connected to the

Scatec's interface connector and to the converter.

After inserting the Y-cable the *Scatec-15* is reconnected fully to the customer's CAN bus.

Note

- In order to insert the Y-cable only the connection to the CAN-bus is for a short time interrupted while the main cable (power supply, encoder input, *Scatec* output) is untouched.
- A *Scatec-15* run without connection to a CAN-bus can be directly connected to the USB-to-Serial-converter with the adapter cable 156261 normally used with a *Scatec-10*.





3 Instructions for use

3.1 General comments on ScaDiag

- ScaDiag can be used with any Scatec model equipped with an interface.
- The operation method of ScaDiag remains the same independent of the Scatec model.
- ScaDiag can be used without a Scatec connected to the PC. For example in the case of pure data analysis. Just click any error message "sensor does not respond".

3.2 How to run ScaDiag

Run *ScaDiag* by double-clicking the file *ScaDiag_E_xxxxxy.exe* or a corresponding link. Make sure that the file *ScaDiag.txt* is in the same directory where *ScaDiag* is executed.



Certain operations (such as tab switching for example) causes *ScaDiag* to communicate with the connected *Scatec*. Failed communication prompts an error message "*sensor does not respond*".



3.3 ScaDiag Main Window



The main window presents a menu bar, a status bar, and the following three panes:

Tab:	all control functions are grouped into several tabs
Graphics pane	displays the measured value of several parameters graphically as plotted over time
File and Cursor Info pane	file info shows information contained in the header of a data file. Cursor info shows details on the cursor position

All three panes can be resized.

All these elements are described in the following sections.



3.4 Menu bar

	SceDiag Baumer Electric			
\langle	File View Options ?			
	Sensor Parameters Counting results Data Communication Download			

File port settings: to define the port used for communication between the Scatec 0 and the PC. to exit the program exit: View to select the tab to be presented as well as to show and hide the 0 toolbar and status bar. Service code: to enter a corresponding password Options 0 ? Info on ScaDiag: to show the ScaDiag version 0 13 × Über ScaDiag οк ScaDiag Version 0.9023 051118a JOATT C Baumer Electric, Frauenfeld Contact Copyright (C) 2005

> Link to the Baumer Electric homepage Prompts an e-mail to Baumer electric (support@baumerelectric.com)

3.5 Tabs





3.5.1 General remarks on the tabs



Whenever the tab is switched *ScaDiag* automatically updates the parameter values shown on the new tab. For this purpose, *ScaDiag* tries to set up a communication with the *Scatec*. If the communication fails, the error message *Sensor does not respond* appears. Simply continue by clicking OK but keep in mind, that no data with the *Scatec* can be exchanged!

3.5.2 Sensor

The Sensor tab appears by default when *ScaDiag* is launched.

Sensor Parameters Counting results Data	a Communication Download
Details on sensor	k
Sensor type	153201 FLDM 170G10/405413
Serial number	484 P-Code 5492
Software version	0.58 051215a Baumer electric AG
Hardware version	161
Communication test	
Test	Ok
Sensor messages	
General message	0
Error message	0
Maintenance	
Sensor restart	Log file for Baumer Electric
from sensor continuously	write to data file

Details on Sensor

• Sensor-Type

Baumer part number and type of the attached Scatec

- Serial number Serial number of the attached Scatec
- o P-Code

0

production date of the attached *Scatec* given in the format (y)ywwd



0	Software-Version	Version of the Scatec operating software
<u>Со</u> о	mmunication test Test	to check if the communication works properly. Does not update the Sensor tab!
<u>Se</u>	nsor Messages	
0	General message	general message given by the Scatec
0	Error message	error message generated by the Scatec
Ma	intenance	
0	Sensor restart	has the same effect as switching off and on the Scatec power supply.
0	Sensor status for BE	to record the complete momentary <i>Scatec</i> status. You will be asked for a directory where to save this file. This file must be saved as binary file (extension: .bin).
		A sensor status for BE should be created whenever Baumer electric is contacted for technical support with a specific <i>Scatec</i> application. This file can be forwarded by e-mail to the applications engineer at Baumer Electric. This

read

0	from sensor	the tab will be updated with data read from the attached Scatec.
0	continuously	the tab will be updated continuously as long as the box is checked.

avoiding many cumbersome queries!

write

o to data file

to create a text file documenting the settings shown in this tab. General information about the attached *Scatec* is saved in the header of this file. A box will pop up asking to enter the directory where the text file should be saved. After saving, an input window pops up allowing adding comments to the text file.

way in one easy step, the complete parameter setting is communicated

In the case of the Sensor tab shown above, *write to data file* would result in the following text file:

🖾 Blatt Sensor.txt - Editor	- 🗆 🗵
Datei Bearbeiten Format ?	
Bheet: Sensor Date: 30.11.05 09:21 Sensor: 153175 FLDM 170G1011/S42 SN: 280 P-Code: 5455 0 Software-Version: 0.58 050623p Baumer electric AG Comments: Beispiel für "Schreiben in Datei" Blatt Sensor	-
ParNr value L 348 0 Sensorfehler 349 1 Sensorinformation	V



3.5.3 Parameters

The Parameter tab helps

- 1. to get an overview on how the parameters of the attached *Scatec* are set
- 2. to change these parameters
- I.) Only parameters are displayed which make sense for the attached Scatec. (for example: with a Scatec-2 attached, no parameters relating to an encoder will show up because a Scatec-2 does not have any encoder inputs)
 - 2.) Parameters stored in the Scatec but not enabled due to the current setting will be shown in grey.
 - 3.) For detailed information on the parameters please refer to the corresponding Scatec manual!
 - 4.) Values changed on the tab will not be effective in the attached *Scatec* unless they are sent by clicking *write to sensor* !
 - 4.) Switching to the Parameter tab will automatically initiate an update of the displayed values by retrieving the actual values from the attached *Scatec*. Further updates have to be triggered by clicking *read from sensor*.

sor Parameters Counting results	Data Communication Do	ownload
Main manager		
- Main parameters		
False pulse suppression	Output pulse length [ms]	10
Oynamic dead time	Dead time [%]	18
Synchronous dead time	Dead anie [%]	
C Fixed dead time	Encoder resolution (mm/puls	e] 1
C Retro-reflective mode	Dead path [mm]	20
Delayed pulse issue	Dead time [ms]	20
Encoder input A&B	o eau anie [me]	
Pulse issue @ end of pulse train	Pulse delay [mm]	100
Short pulse suppression	Pulse delay [ms]	100
Edges trailing	C analtinitu	la bish
Customized sensitivitu	Sensitivity	i nign 💌
Customized sensitivity	Edge: threshold	197
	Edge: hysteresis	32
- Sensor connected to CAN network		
Thickness-compens, pulse issue	e ,, ,	0
Insert missing pulse	Mean overlap	lo.
I maert missing pulse	Conu thickness [mm]	0
Self-adjusting sensitivity	coblementations [unu]	1-
	Copy length [mm]	0
Sensor CAN-controlled	CAN-simula	ation by PC
read	write	
from sensor	Islu to concer	
Continuou	to sensor	default
		Values ro
from data file	to data file	sensor



Main parameters

A checked box or a filled round button indicates that the corresponding function with its parameter value is enabled. The meaning of the parameter and its value is explained in the corresponding *Scatec* manual.

<u>read</u>

from sensor
 from data file
 from data file
 The Parameter tab will be updated with data read from the attached Scatec.
 The Parameter tab will be updated with data read from a text file. This text file must be of the same structure as a text file created by clicking write to data file on the same tab.

<u>write</u>

- o to sensor
- o to data file

The values displayed on the Parameter tab will be transmitted to the attached *Scatec*. Immediately afterwards, the Parameter tab will be updated with the actual values in the *Scatec*. This allows the user to check if all the values were accepted.

To create a text file documenting the settings as shown on the Parameter tab, along with the general sensor information about the attached *Scatec*. A box will pop up asking for a directory where to save the text file. After the file is saved, an input window pops up that allows adding a comment to the text file.

Write to data file documents the settings as they are shown on the Parameter tab. If the user made any changes on the Parameter tab, the settings shown on the tab might differ from the settings in the attached *Scatec* unless the Parameter tab has been updated by clicking on *read from sensor*.

In the case of the Parameter tab shown above, *write to data file* would result in a text file with the following content:

Datei Bearbeiten Format ?	erung.txt - Editor
Sheet: Parametrierung L	Format ?
Sensor: 153175 FLDM 170g1011/542 SN: 280 P-Code: 5455 0 Software-version: 0.58 050623p Baumer electric Ag Comments: Beispiel zu "Schreiben in Sensor" auf Blatt "Parametrierung"	etrierung L .05 14:34 5 FLDM 170G1011/542 0 ion: 0.58 050623p Baumer electric AG spiel zu "Schreiben in Sensor" auf Blatt "Parametrierung"
PainWainProg. Select266131MainProg. Select2670Prog. Details26820Deadtime dynamic26910Deadtime27012Deadway271200Out Duration2721Edge Sens.273212Threshold27434Hysterese275100Sync. Resolution27630Pulsausgabeverzögerung [ms]27720Pulsausgabeverzögerung [mm]3360Mittl. Schuppenabstand3370Exemplarldicke3380Exemplarldicke3452Operationmode	Main Prog. Select Prog. Details Deadtime dynamic Deadtime Deadway Out Duration Edge Sens. Threshold Hysterese Sync. Resolution Pulsausgabeverzögerung [ms] Pulsausgabeverzögerung [mm] Mittl. Schuppenabstand Exemplarldicke Exemplarldicke Exemplarldinge Operationmode



Application note:

write to data file is an easy way to document different versions of parameter settings. At a later time, one of these versions can be easily reloaded to a *Scatec* in two steps: First, update the Parameter tab by clicking *read from data file* and choosing the file where this specific version was documented. Than send these parameter values to the attached *Scatec* by clicking on *write to sensor*.

default values to sensor to recall the default setup. The Scatec is set up for normal operation when it is shipped from the factory. This is the default setup. The default setup cannot be altered by the customer and is documented in the corresponding manual. Note, that values specifying the CAN communication parameters shown on the Communications tab will not be affected by this reset procedure.

3.5.4 Counting results

Sensor	Parameters Counting result	Data Communication Download
_ C	ounting results	
1	Total of counted edges (=100%) 92 Reset
ſ	marginally counted edges	51.0870 % 47
r	marginally missed edges	82.6086 % 76
S	ensor messages	
(General message 0	
E	Error message 0	
	from sensor	uously



Counting results

0	Total of counted edges	number of issued Scatec output pulses
0	Reset	used to set the counters back to 0
0	Marginally counted edges	number as percentage and absolute value

Marginally missed edges number as percentage and absolute value

Sensor-messages

0	General message	general message given by the Scatec (Code-number and description)
0	Error message	error message generated by the Scatec (Code-number and
		description)

read

0

o From sensor

write

o To data file

The Counting result tab will be updated with data read from the attached *Scatec*.

To create a text file documenting the settings as shown on the Counting results tab together with the general sensor information about the attached *Scatec*. A box will pop up asking for a directory where to save the text file. After the file is saved, an input window pops up allowing comments to be added to the text file.

In the case of the Parameter tab shown above, *write to data file* would result in a text file with the following content:

🌌 Blatt Zá	ihlresultate	e.txt - Editor		- D ×
Datei Bea	rbeiten For	mat ?		
Sheet: Date: Sensor: SN: P-Code: Softwar Comment:	Zählres 01.12.0 151988 111 4495 e-Versio s: Beisp	ultate 5 11:55 FLDK 110G1003/S14 1 n: 0.58 05052 iel zu Schreiben in] Oj Baumer electric AG Datei, Blatt Zählresu	Itate
ParNr 339 341 343 348 348	value 248 29 15 0 0	Totalisator kritische Zählereig krit. Ereignisse oh Sensorfehler Sensorinformation	nisse ne Zählpuls	Y



3.5.5 Data

On the Data tab, all functions relating to recording, saving, displaying, and analyzing data are listed. The button operation is closely based on the operation of an oscilloscope.

All the necessary settings are performed on the Data tab while the results are displayed in the Graphics, File info and Cursor info pane

Sensor Parameters Counting result Data Communication Download
Sampling set log file load Data file logging Start save Data Hold display Find C IN prev next O DEAD O UT
Time (horizontal) Scale Q Q 10 [ms] Position 4545.84 Scrollbar starts at [ms]
Y-value (vertical) Y-Value Min Max Y-Scale Graph A 0 1000 0 Graph B 0 1000 0
Plots Graph 🔽 show digital signals
A Parameter Nr. Image: Comean Comin Comax Copeak A Parameter Nr. Image: Comean Comin Comax Copeak A Parameter Nr. Image: Comean Comin Comax Copeak A Parameter Nr. Image: Comean Comin Comax Copeak

Sampling:

o set log file

To enter the file name and the directory on where to save the data. On saving data, the entered file name will automatically be expanded by an appendix consisting of the time stamp when the file was saved. Log files are saved as binary files. Therefore the name of a saved log file will have a structure as follows: name_appendix.bin with name: name as entered by user after clicking set log file appendix time stamp, format yymmdd_hhmm_ss By default the name is SCATEC and the directory is the desktop.



0	file logging	Enabled file logging causes data to be saved periodically between pressing the <i>start</i> and <i>stop</i> button. The sampled data is saved in files with names as described under <i>set log file</i> . Note that all files generated during such a run will later be recognized as belonging together.
		 Application notes: Data files generated this way do have a size of about 1.4 Mbyte. with 1 analog parameter recorded (by default), 1.4 Mbyte covers about 57
		seconds (every 0.120 ms a record); with 2 analog parameters recorded, 1.4 Mbyte
		covers about 68 (!) seconds (every 0.240 ms a record).
0	Start	to start data recording.
0	Stop	to stop data recording
0	save Data	Shown only when file logging is disabled. To save the data contained in the RAM to a data file. The file name will be as defined under <i>set log file</i> . Please note that only data buffered in the RAM will be saved. Therefore only the last part of a longer recording run will be saved. Should all data of the complete run be saved then file logging must be enabled before starting the data recording.
0	load Data	To load previously saved data for analysis. The user will be prompted to choose a file name. Keep in mind, that not only the entered file will be loaded, but all other data files belonging to the same run. The data of all these files will be joined and displayed in the correct chronological sequence.
<u>Triç</u>	<u>gger:</u>	
Мо	de:	
0	Scroll	the displayed graphic is continuously updated while new data is recorded.
0	Trigger	The update of the displayed graphic is initiated by the occurrence of an event defined in the box <i>digital signals</i> .
0	hold display	While <i>hold display</i> is enabled, the graphic is not updated.
Dig	jital signals:	
0	pos. edge	The rising edge of the respective digital signal is used for the trigger. With the button disabled, the falling edge of the respective digital signal is used for the trigger.
0	ENCD	Trigger source is the encoder signal. Note that the correct display of the encoder pulses requires an adequate resolution of the time axis.
0	REFL	Trigger source is the digital signal of the retro-reflective sensor. <i>REFL</i> is high as long as the laser beam hits the retro-reflective foil.
0	CRIT	Trigger source is a critical event.
0	IN	Trigger source is the digital signal <i>IN</i> . <i>IN</i> goes high when the analog signal <i>ratio f/b</i> falls below the actual threshold and it goes low when this analog signal raises again above the actual threshold plus hysteresis.
0	DEAD	Trigger source is the digital signal dead time. <i>DEAD</i> is high while a dead time is activated.
0	OUT	Trigger source is the output pulse. OUT is high while <i>Scatec</i> issues an output pulse.
Fin	d	
0	prev.	The waveforms in the display are shifted to the right until the previous trigger event gets to the position of the trigger line T. (how to set the trigger position see section 3.6 Graphics pane)



0	next	The waveforms in the display are shifted to the left until the next trigger event gets to the position of the trigger line T. (how to set the trigger position see section 3.6 Graphics pane)
Tim	<u>ne (Horizontal):</u>	controls the horizontal scale of the waveforms
0	Scale	The <i>magnifying glass</i> zooms in on and out off the center of the displayed plot.
0	Position	> displays data previously outside the graphics on the right side. Changes you make to this control do not affect the actual scale.
		make to this control do not affect the actual scale.
0	Scrollbar starts at	Plots start at this time with the x-scroll bar fully to the left. (This is an easy way to bring a specific time section of the data into display.)
<u></u> Y-∖	/alue (Vertical):	controls the vertical scale of the analog waveform
0	Y-Value Min	Y-axis starts at this value
0	Y-Value Max	Y-axis ends at this value

Plots:

0	Parameter Nr.	Scatec transmits the values for either one or two analog parameters depending on
		the setting. Parameter Nr. Defines which one of the two parameter values will be
		displayed in the graphic. By default, Scatec sends the values of only one analog
		parameter, namely the ratio f/b.

- Depending on the time scale of the plot not every single data point sent by the *Scatec* can be assigned to a single pixel. In such cases, a set of data points will be combined into one pixel. There are four combination modes:
- *mean* displayed is the mean value of the set of data points to be combined.
- o *min* displayed is the minimum value of the set of data points to be combined.
- o *max* displayed is the maximum value of the set of data points to be combined.
- *peak* displayed is alternatively the maximum and the minimum value of the set of data points to be combined.

Note that the combination mode affects only the display, while the data stored in the RAM or in files are not reduced in any way.

Application note:

With a large time scale, the waveforms displayed will vary depending on the combination mode. For example short edges will no longer be visible in the waveforms when *mean* was chosen as combination mode because glitches will be suppressed by the averaging. In such a case, choose *min* or *peak* – mode if glitches still should be displayed!



3.5.6 Communication

The communication tab allows the setting of parameters relating to the CAN interface if the attached *Scatec* is equipped accordingly. The parameters listed in this tab are explained in the *Scatec* CAN-manual.

Sensor Parameters Counting results	Data Communication Download
CAN-Interface	
CAN-baud rate	500 kBaud 💌
CAN-node number	le C
Heart beat [ms]	0
Node-Guarding [ms]	1028
Life-Time-Factor (Node Guard)	60
	uslu to sensor
from data file	to data file sensor

3.5.7 Download

With the proper authorization, this tab allows downloading new Scatec operating software into the Scatec.





3.6 Graphics pane

In the graphics box, plots of various signals versus time are shown. Plots of digital signals are displayed in the upper part of the box while plots of analog signals are shown in the lower part of the box. The time scale is the same for all plots.

Digital signals:	
ENCD	encoder pulses. Note that correct display of the encoder pulses requires an adequate resolution of the time axis.
REFL	signal of the built-in retro-reflective sensor. The signal is high as long as the laser beam of the <i>Scatec</i> hits the retro-reflective foil.
CRIT	Critical count. The signal goes high for 3 ms when a critical count (marginally missed or detected edge) was detected.
IN	<i>IN</i> goes high when the analog signal <i>ratio f/b</i> falls below the actual threshold and it goes low when this analog signal raises again above the value (actual threshold + hysteresis). The yellow edge indicator LED of the <i>Scatec</i> lights while <i>IN</i> is high.
DEAD	DEAD is high while a dead time is activated.
OUT	OUT is high while <i>Scatec</i> issues an output pulse.
Analog signals	
Analog signal	by default the analog signal <i>ratio f/b</i> is plotted. (for the meaning of the analog signal <i>ratio f/b</i> refer to the Scatec-manual)



X-axis (horizontal)	time axis, labeled with milliseconds. The time base can be adjusted on the tab <i>Data</i> , <i>Time (horizontal).</i>	
Y-axis (vertical)	signal values are shown on the Y-axis. The vertical scale can be adjusted o the tab <i>Data</i> , Y-Value (Vertical).	
Setting the Trigger and C	Cursor position:	
Trigger:	move the mouse to the appropriate position in the graphic and click the left mouse button while <i>shift</i> key is held down. A vertical line appears on the display labeled with a <i>T</i> .	
Cursor:	move the mouse to the appropriate position in the graphics and click the left mouse button. A vertical line appears on the display labeled with a <i>C</i> . Right after setting the cursor it can be moved with the <i>right / left</i> key.	

3.7 File Info and Cursor Info pane

File Info		Cursor Info
File name	no File, Data from RAM	relative position 4742.4 ms
		absolute position 04.01.06 19:05:39
	_	ENCD 0 REFL 0 CRIT 0
Recording period	04.01.06 19:05:34 - 04.01.06 19:05:42	IN O DEAD O OUT O
Sensor type	153201 Serial righter 484	min mean max
Software version	0.58 051215a Baumer electric AG	Param 1 300 327 354
Hardware version	161 Raw data type 101	Param 2 0 0 0

File Info

0	File Name	name of the file to which measurement data is saved or name of the file which was chosen on clicking the <i>load data</i> button. In the box underneath all file names belonging to the same measurement run are listed. The data of all these files are automatically connected and displayed in the graphics box.
0	Recording period	start and end time of the measurement run.
0	Sensor type	part number of the Scatec which was used for the data acquisition.
0	Serial number	serial number of the Scatec which was used for the data acquisition.
0	Software-Version	version of the operating software of the <i>Scatec</i> which was used for the data acquisition.
0	Hardware-Version	version of the electronics in the Scatec which was used for the data acquisition
0	Raw data type	code for the analog parameter which was recorded. By default the parameter <i>ratio</i> f/b is recorded which has the code (raw data type) 101.



Cursor Info

- o *relative position* cursor position relative to the start of the measurement run.
- *absolute position* absolute time of the cursor position.
- ENCD, REFL, CRIT, IN, DEAD, OUT values of the according digital parameters at the position of the cursor. (on the plots, value 1 is high and value 0 is low)
- *Param 1, 2* values of the respective analog parameters at the position of the cursor. (Note that by default only one analog parameter is recorded, the *ratio f/b*)

min, mean, max: minimum, mean, and maximum value of the set of data points represented by the pixel at the cursor position.



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